Hamburg University of Technology Institute for Fluid Dynamics and Ship theory

Dealing with consistent kernel-based approximations and variable resolution in Dual SPHysics

Marzia Leonardi, Jose M. Dominguez, Thomas Rung



3rd DualSPHysics Workshop

November 14th, 2017





- Objectives and Motivations
- Existing Strategies
- Explicit Consistency Corrections
- Variable Resolution Approach
- Results
- Concluding Remarks



Objectives and Motivations

- Objectives and Motivations
- Existing Strategies
- Explicit Consistency Corrections
- 4 Variable Resolution Approach



Consistency is a key issue

. . .

Objectives and Motivations

Convergence requires consistency (and not only ... Lax-Richtmyer)

• Order of consistency depends on degree of polynomial that can be reproduced by the kernel approximation.

$$\begin{array}{lll} \text{Oth order: } f(x) = a & \sum V_j \left| \overrightarrow{W_{ij}} \right| = 1 & \sum V_j \left| \overrightarrow{W_{ij}^{\alpha}} \right| = 0 \\ \text{1st order: } f(x) = ax + b & \sum V_j \left| \overrightarrow{W_{ij}} \right| \Delta x_{ji}^{\alpha} = 0 & \sum V_j \left| \overrightarrow{W_{ij}^{\alpha}} \right| \Delta x_{ji}^{\beta} = \delta^{\alpha\beta} \\ \text{2nd order: } f(x) = ax^2 + bx + c & \sum V_j \left| \overrightarrow{W_{ij}} \right| \Delta x_{ji}^{\alpha} \Delta x_{ji}^{\beta} = 0 & \sum V_j \left| \overrightarrow{W_{ij}^{\alpha}} \right| \Delta x_{ji}^{\alpha} \Delta x_{ji}^{\beta} = 0 \end{array}$$

• Different (moment) criteria evolve depending on the operator that is observed (function, gradients, second derivatives, etc.)



Consistency

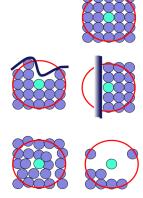
Consistency problems are associated to level of anti-symmetry of the discrete kernel sampling.

Practical relevance

- Truncated kernel supports (e.g. boundaries or free surfaces);
- Isolated particles:
- Irregular particle distributions.

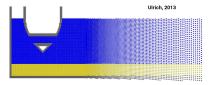
Life can be hard!

Problems related to many famous SPH topics with many famous work-arounds models





Many marine/coastal engineering problems (e.g. a ship hull in a full-scale water basin) require a lot of particles.



Practical relevance

- Large computation domains;
- Domains in which a confined region requires higher resolution;
- No high-perfomance computing avalaible.



- Objectives and Motivations
- Existing Strategies
- Explicit Consistency Corrections
- 4 Variable Resolution Approach



Manipulate/regularise discretisation/particle samples.

shift particles, introduce ghost/fixed wall particles, ...

Manipulate kernel-based approximation.

- Apply **Shepard** normalisation (0th-order consistency) of kernels. Limited impact since function approximations are rare in PDEs.;
- Correct kernel + gradients following a minimization procedure (MLS);
- Correct kernel + gradients + higher derivatives from Max.Entropy option (Ortiz and Sukumar);
- Correct kernel + gradients + higher derivatives with weitghed residuals (Liu², Chen and Beraun);



Manipulate/regularise discretisation/particle samples.

shift particles, introduce ghost/fixed wall particles, ...

Manipulate kernel-based approximation.

with MLS, MaxEnt, weighted residuals...

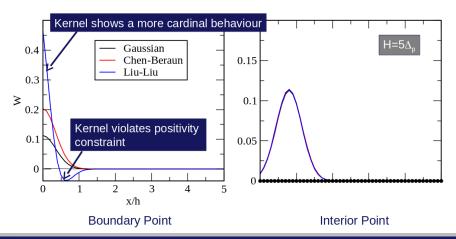
Disadvantages

- limited success for FS-flows, due to violation of positivity constraint;
- conflict between conservation on particle level and consistency;
- significant computational effort to satisfy constraints (implicit 4X4 [10X10] systems at each point and time for order 1[2]).



Consistency

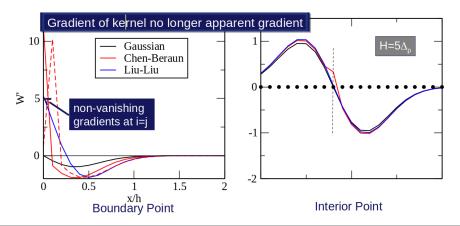
Apparent kernels (1st order)





Consistency

Apparent kernel gradients $(1^{st} order)$





Inhomogeneous particle distribution in the domain (e.g. Omidvar et al.) NOT DYNAMIC: Retaining of particles properties/number during simulation time. Not suitable for violent dynamics and big deformations.

Merging/Splitting variable resolution techniques (e.g. Barcarolo, Feldman, Vacondio et al.)

DYNAMIC: Particles number, properties and locations change in time (in compliance with conservation of mass and momentum).



Wishful thinking

We desire

- Cheap, preferably explicit correction;
- Focus on gradient approximation;
- Directly applied in discrete space (inherently adjust to actual sampling);
- Easy and natural access to Dirichlet and Neumann conditions;
- Build from familiar kernels and Re-castable into familiar frame (apparent W_{ii} and W'_{ii}).

We also desire

- Coupling of consistent SPH approximations with a variable resolution scheme:
- A dynamic (or partially dynamic) variable resolution approach.



- Objectives and Motivations
- Existing Strategies
- Explicit Consistency Corrections
- 4 Variable Resolution Approach



Desired achievable order

- 1st order sufficient for most cases;
- ullet 2nd order has debatable features (jumps and inevitable loss of positivity).

Focal point

 is on the gradient rather than functions (no need); build from standard kernels

Design principle

- 3 conditions can be implemented explicitly in discrete space (+3 loops);
- this is sufficient to perform 3 x 1D up to 2_{nd} order but not 1_{st} order 3D;
- correction refer to kernel counterparts (symmetrical unsymmetrical);
- priority given to robustness (mollified correction) rather than accuracy.



Kernel Gradient Correction (example)

Gradient is anti-symmetric - thus correction is symmetric (= kernel) (Truncation of W' strives for symmetry - truncation of W strives for opposite) As opposed to Chen and Beraun the correction is mollified around the focal point

$$\tilde{W}'_{ij} = W'_{ij} + \alpha W_{ij}$$

Conditions (3 X 1D, i.e. ignore symmetry conditions normal to differentiation)

$$\sum_{j} V_{j} \tilde{W}'_{ij} = 0 \qquad \sum_{j} V_{j} \tilde{W}'_{ij} (x_{j} - x_{i}) = 1 \qquad \sum_{j} V_{j} \tilde{W}'_{ij} (x_{j} - x_{i})^{2} = 0$$

Normalisation conditions are always implemented at the end.



Kernel Gradient Correction (example)

Gradient is anti-symmetric - thus correction is symmetric (= kernel) (Truncation of W' strives for symmetry - truncation of W strives for opposite) As opposed to Chen and Beraun the correction is mollified around the focal point

$$\tilde{W}'_{ij} = W'_{ij} + \alpha W_{ij}$$

Conditions (3 X 1D, i.e. ignore symmetry conditions normal to differentiation)

$$\boxed{\sum_{j} V_{j} \tilde{W}_{ij}' = 0} \qquad \sum_{j} V_{j} \tilde{W}_{ij}'(x_{j} - x_{i}) = 1 \qquad \sum_{j} V_{j} \tilde{W}_{ij}'(x_{j} - x_{i})^{2} = 0$$

Start with 1_{st} order Consistency

$$\beta = \sum_{i} V_{i} W'_{ij}$$
 $\gamma = \sum_{i} V_{i} W_{ij}$ \rightarrow $\hat{W}'_{ij} = W'_{ij} - \frac{\beta}{\gamma} W_{ij}$



Kernel Gradient Correction (example)

Gradient is anti-symmetric - thus correction is symmetric (= kernel) (Truncation of W' strives for symmetry - truncation of W strives for opposite) As opposed to Chen and Beraun the correction is mollified around the focal point

$$\tilde{W}'_{ij} = W'_{ij} + \alpha W_{ij}$$

Conditions (3 X 1D)

$$\sum_{i} V_{j} \tilde{W}'_{ij} = 0$$

$$\sum_{j} V_{j} \tilde{W}'_{ij} = 0 \qquad \left[\sum_{j} V_{j} \tilde{W}'_{ij} (x_{j} - x_{i}) = 1 \right] \qquad \sum_{j} V_{j} \tilde{W}'_{ij} (x_{j} - x_{i})^{2} = 0$$

$$\sum_{j} V_{j} \tilde{W}_{ij}'(x_{j} - x_{i})^{2} = 0$$

Perform final normalisation which does not alter previous constraints

$$ilde{W}_{ij}^{'}=rac{\hat{W}_{ij}^{'}}{\sum_{j}V_{j}\hat{W}_{ij}^{'}(x_{j}-x_{i})}$$



Kernel Gradient Correction (example)

Gradient is anti-symmetric - thus correction is symmetric (= kernel) (Truncation of W' strives for symmetry - truncation of W strives for opposite) As opposed to Chen and Beraun the correction is mollified around the focal point

$$\tilde{W}'_{ij} = W'_{ij} + \alpha W_{ij}$$

Conditions (3 X 1D)

$$\sum_{j}V_{j} ilde{W}_{ij}'=0 \qquad \sum_{j}V_{j} ilde{W}_{ij}'(x_{j}-x_{i})=1 \qquad \boxed{\sum_{j}V_{j} ilde{W}_{ij}'(x_{j}-x_{i})^{2}=0}$$

Also 2_{nd} Order Consistency can be derived in a similar way.

$$\zeta = \sum_{j} V_{j} W_{ij} (x_{j} - x_{i})^{2} \qquad \psi = \sum_{j} V_{j} W'_{ij} (x_{j} - x_{i})^{2} \qquad \rightarrow \qquad \hat{W}'_{ij} = W'_{ij} - \frac{\psi}{\zeta} W_{ij}$$



Kernel Gradient Correction (example)

Gradient is anti-symmetric - thus correction is symmetric (= kernel) (Truncation of W' strives for symmetry - truncation of W strives for opposite) As opposed to Chen and Beraun the correction is mollified around the focal point

$$\tilde{W}'_{ij} = W'_{ij} + \alpha W_{ij}$$

Conditions (3 X 1D)

$$\sum_{j} V_{j} \tilde{W}'_{ij} = 0$$

$$\sum_{j} V_{j} \tilde{W}'_{ij} = 0 \qquad \left[\sum_{j} V_{j} \tilde{W}'_{ij} (x_{j} - x_{i}) = 1 \right] \qquad \sum_{j} V_{j} \tilde{W}'_{ij} (x_{j} - x_{i})^{2} = 0$$

$$\sum_{j} V_{j} \tilde{W}_{ij}'(x_{j} - x_{i})^{2} = 0$$

Perform final normalisation which does not alter previous constraints

$$ilde{W}_{ij}^{'}=rac{\hat{W}_{ij}^{'}}{\sum_{j}V_{j}\hat{W}_{ij}^{'}(x_{j}-x_{i})}$$



Kernel Gradient Correction (example)

Gradient is anti-symmetric - thus correction is symmetric (= kernel) (Truncation of W' strives for symmetry - truncation of W strives for opposite) As opposed to Chen and Beraun the correction is mollified around the focal point

$$\tilde{W}'_{ij} = W'_{ij} + \alpha W_{ij}$$

Conditions (3 X 1D)

$$\sum_{j} V_j \tilde{W}'_{ij} = 0$$
 $\sum_{j} V_j \tilde{W}'_{ij} (x_j - x_i) = 1$ $\sum_{j} V_j \tilde{W}'_{ij} (x_j - x_i)^2 = 0$

 0_{th} -order condition implemented at focal point W'_{ii} since this has no influence on second order constraint (unmollified correction)

$$ilde{W}_{ii}^{'} = -\sum_{i
eq i} ilde{W}_{ij}^{'}$$



Kernel Function

Kernel Gradient

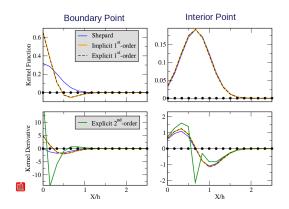
$$\begin{split} \tilde{W_{ij}} &= W_{ij} + \alpha W_{ij}' & \tilde{W_{ij}'} &= W_{ij}' + \alpha W_{ij} \\ \sum_{j} V_{j} \hat{W_{ij}}(x_{j} - x_{i}) &= 0 \rightarrow \alpha = -\frac{\sum_{j} V_{j} W_{ij}(x_{j} - x_{i})}{\sum_{j} V_{j} W_{ij}'(x_{j} - x_{i})} & \sum_{j} V_{j} \hat{W_{ij}'} &= 0 \rightarrow \alpha = -\frac{\sum_{j} V_{j} W_{ij}'}{\sum_{j} V_{j} W_{ij}} \\ \sum_{j} V_{j} \tilde{W_{ij}} &= 1 \rightarrow \tilde{W_{ij}} & \sum_{j} V_{j} \tilde{W_{ij}'}(x_{j} - x_{i}) &= 1 \rightarrow \tilde{W}_{ij}' &= \frac{\hat{W_{ij}'}}{\sum_{j} V_{j} \hat{W_{ij}'}(x_{j} - x_{i})} \end{split}$$

Key idea: to bias a (sufficient) quantity α of an even function in case of an uneven function, and vice versa.

The consistency constraints (0th, 1st and 2nd-order conditions) give a measure of the needed α .



Comparison of different approaches





Some remarks

- Kernel, kernel gradient and higher-order correction are performed individually in the discrete space:
- there is no simple formal link between these properties anymore;
- Kernel function symmetry / kernel gradient anti-symmetry is lost. Conservation is also lost:
- Negative kernel values occur;
- Neumann condition can be imposed by means of equivalent Dirichlet condition

$$\overline{f}_i' = \sum_{i \neq i} V_j \tilde{W}_{ij}' f_j + V_i \tilde{W}_{ii}' f_i \qquad o \qquad \left| f_i = rac{\overline{f_i'} - \sum_{j \neq i} V_j \tilde{W}_{ij}' f_j}{V_i \tilde{W}_{ii}'} \right|$$

$$f_i = \frac{\overline{f_i'} - \sum_{j \neq i} V_j \tilde{W}_{ij}' f_j}{V_i \tilde{W}_{ii}'}$$



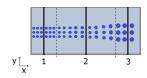
- Objectives and Motivations
- Existing Strategies
- Explicit Consistency Corrections
- Variable Resolution Approach



Variable Resolution

Eulerian Variable Resolution Scheme

Following a route by Ulrich et al.



The analytical definition of the kernel function (and of its gradient) is supplemented by a term addressing the **spatial variation of the kernel**

$$\nabla W_{ij} = \frac{\partial W_{ij}}{\partial r} \nabla r + \frac{\partial W_{ij}}{\partial h} \nabla h$$

The Navier-Stokes equation are also supplemented with appropriate source terms, accounting for the **variation of particle masses**

$$S_{CE} = \sum_{j=1}^{N} V_{j} v_{j}^{\alpha} \frac{\partial \rho_{j}}{\partial x_{j}^{\alpha}} W_{ij} = \sum_{j=1}^{N} v_{j}^{\alpha} \frac{\partial m}{\partial x_{j}^{\alpha}} W_{ij}$$

$$S_{ME} = -\sum_{j=1}^{N} \frac{v_{i}^{\alpha}}{m_{i}} \frac{m_{j}}{\rho_{j}} \left(v_{j}^{\beta} \frac{\partial m}{\partial x_{j}^{\beta}} W_{ij} \right)$$



- Objectives and Motivations
- Existing Strategies
- Explicit Consistency Corrections
- 4 Variable Resolution Approach
- Results



- Objectives and Motivations
- Existing Strategies
- Explicit Consistency Corrections
- 4 Variable Resolution Approach
- Concluding Remarks



- Significant response to kernel gradient correction on preliminary validation 1D and 2D test cases. → The consistency of the kernel gradient has been increased at a low computational cost (max 3 loops);
- ullet It is possible to apply **Neumann boundary condition**; o gradient of the kernel function is not 0 in the focal point!
- No additional row of particles have been used to mimic the wall, as remedy to boundary truncation.
- The coupling of KGC with VR delivered good results with both hydrostatic and dynamic cases;
- The use of VR reduces significantly the total amount of particles needed (circa 50 percent).



- It will be will be tested using 3D test cases/more complex geometries;
- Improvement of Pre- and Postprocessing procedures (slightly different from standard DualSHysics tools, due to variable resolution);
- **Upgrade** to the last version of DualSPHysics is planned.





Hamburg University of Technology Institute for Fluid Dynamics and Ship theory

Dealing with consistent kernel-based approximations and variable resolution in Dual SPHysics

Marzia Leonardi, Jose M. Dominguez, Thomas Rung



3rd DualSPHysics Workshop

November 14th, 2017



